# Two-scale numerical modelling of flow in porous media with fine-scale heterogeneity

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#### Part I:

# Unsaturated water flow in a two-dimensional binary medium

Joint work with Ian Turner (QUT) and Patrick Perré (ECP)

#### Unsaturated water flow

- Immiscible two-phase (air and water) flow
- ▶ Darcy's Law (phase  $\alpha$ ):

$$\boldsymbol{q}_{\alpha} = -\frac{k_{\mathrm{r},\alpha}}{\mu_{\alpha}} K \left( \nabla p_{\alpha} - \rho_{\alpha} \boldsymbol{g} \right)$$

- Capillary pressure  $p_c = p_a p_w$
- Mass conservation (phase  $\alpha$ ):

$$\frac{\partial \left(\rho_{\alpha}\phi S_{\alpha}\right)}{\partial t} + \nabla \cdot \left(\rho_{\alpha}\boldsymbol{q}_{\alpha}\right) = 0$$

where  $S_w + S_a = 1$ 



## **Richards' equation**

- Model assumptions:
  - (i) air phase is at a constant and atmospheric pressure
  - (ii) water phase is incompressible and of constant density
- Single equation for the water saturation:

$$\frac{\partial \theta}{\partial t}(h) + \nabla \cdot \left(-K(h)\left(\nabla h + \nabla y\right)\right) = 0$$

where  $h = p_c/(\rho_w g)$  is the capillary pressure head,  $\theta = \phi S_w$  is the moisture content and K is the hydraulic conductivity.

Closure relationships [van Genuchten (1980)]:

$$\theta(h) = \theta_{\rm res} + (\theta_{\rm sat} - \theta_{\rm res})S_e(h)$$
$$K(h) = K_{\rm sat}\sqrt{S_e} \left(1 - \left(1 - S_e^{1/m}\right)^m\right)^2$$
$$S_e(h) = (1 + (-\alpha h)^n)^{-m}$$

with hydraulic parameters  $\theta_{\rm res}$ ,  $\theta_{\rm sat}$ ,  $\alpha$ , n and m.

#### **Fine-scale model**

**Binary medium**: Domain comprised of two sub-domains  $\Omega_a$  (connected) and  $\Omega_b$  (inclusions):

$$\begin{split} \theta(h) &= \begin{cases} \theta_a(h) & \text{in } \Omega_a \\ \theta_b(h) & \text{in } \Omega_b \end{cases} \\ K(h) &= \begin{cases} K_a(h) & \text{in } \Omega_a \\ K_b(h) & \text{in } \Omega_b \end{cases} \end{split}$$

Richards' equation in a binary medium (i = a, b):

$$\frac{\partial \theta_i}{\partial t}(h_i) + \nabla \cdot \left(-K_i(h_i)\left(\nabla h_i + \nabla y\right)\right) = 0$$



Heterogeneous domain  $\Omega_a \blacksquare \quad \Omega_b \blacksquare$ 

Computational cost of direct numerical simulation is prohibitively expensive when the domain exhibits small-scale heterogeneity.

#### Two-scale computational model

**Macroscopic equation:**  $h_a(x,t)$  ( $x \in \Omega$ )

$$\frac{\partial \theta_{\text{eff}}}{\partial t}(h_a) + \nabla \cdot \left(\mathbf{K}_{\text{eff}}(h_a)\left(\nabla h_a + \nabla y\right)\right) = S$$

**Microscopic equation:**  $h_{b,i}(x,t)$  ( $x \in C_{i,b}$ )

$$\frac{\partial \theta_b}{\partial t}(h_{b,i}) + \nabla \cdot \left( K_b(h_{b,i}) \left( \nabla h_{b,i} + \nabla y \right) \right) = 0$$

#### Coupling between scales:

- (i) Microscopic boundary condition:  $h_{b,i}(x,t) = h_a(x,t) \ (x \in \Gamma_i)$
- (ii) Source term *S* represents the exchange of water between the two sub-domains and is recovered numerically from the micro-cell problems

#### Szymkiewicz and Lewandowska (2006) Carr and Turner (2014), Carr et al. (2015)



Macro mesh on  $\Omega$ 

## **Spatial discretisation**

Control Volume Finite Element discretisation [Carr et al. (2015)]



## Imaged-based meshing of micro-cells

Image-based mesh generation using GMSH [Carr and Turner (2014)]



#### Semi-discrete system of ODEs

▶ Spatial discretisation can be expressed in the form [Carr et al. (2015)]

$$rac{doldsymbol{u}}{dt}=oldsymbol{g}(oldsymbol{u})\,,\quadoldsymbol{u}(0)=oldsymbol{u}_0\in\mathbb{R}^N\,,$$

where  $N = n_{macro_nodes} + n_{macro_elements} \times n_{micro_nodes}$ .

**Example:** Sparsity pattern of the Jacobian matrix of g(u) (zoomed in)



#### Time stepping: exponential integrator

Exponential Rosenbrock-Euler Method [Carr et al. (2011, 2013)]:

$$rac{doldsymbol{u}}{dt} = oldsymbol{g}(oldsymbol{u}) \quad \stackrel{ ext{Linearise}}{=} \quad rac{doldsymbol{u}}{dt} = oldsymbol{g}_n + oldsymbol{J}_n(oldsymbol{u} - oldsymbol{u}_n)$$

where  $\boldsymbol{g}_n = \boldsymbol{g}(\boldsymbol{u}_n)$  and  $\boldsymbol{J}_n = \boldsymbol{J}(\boldsymbol{u}_n)$ , and solve exactly over a single time step:

$$oldsymbol{u}_{n+1} = oldsymbol{u}_n + au_n arphi( au_n oldsymbol{J}_n) oldsymbol{g}_n$$

where  $\varphi(\mathbf{A}) = \mathbf{A}^{-1}(e^{\mathbf{A}} - \mathbf{I}).$ 

- Explicit scheme
- Krylov subspace methods for computing φ(τ<sub>n</sub>J<sub>n</sub>)g<sub>n</sub> converge rapidly without preconditioning, and require only matrix-vector products with J<sub>n</sub>:

$$\boldsymbol{J}_{n}\boldsymbol{v}\approx\frac{\boldsymbol{g}(\boldsymbol{u}_{n}+\varepsilon\|\boldsymbol{v}\|_{2}\boldsymbol{v})-\boldsymbol{g}(\boldsymbol{u}_{n})}{\varepsilon\|\boldsymbol{v}\|_{2}}\,,\quad\varepsilon\approx10^{-8}$$

#### Code implementation details

- ▶ Both fine-scale and two-scale codes developed in C++
- ▶ Linear algebra operations performed using BLAS and LAPACK libraries:
  - (a) Intel MKL (HPC Platform)
  - (b) Accelerate framework (Macbook Pro)

ODE right-hand side function g(u) implemented in parallel using OpenMP

```
#include <omp.h>
omp_set_num_threads(NUM_THREADS);
#pragma omp parallel for
for (k=0; k<n_macro_elements; k++)
{
....
}</pre>
```

▶ Code accommodates both triangular and quadrilateral elements at both scales



Fine-scale:208, 676 triangular elements and 104, 859 nodes [N = 104, 859]Two-scale:20  $\times$  20 grid and 441 nodes (macro mesh)264 triangular elements and 153 nodes (micro mesh) [N = 61, 641]

Saturation contours after 25 hours:



(Runtime: 2 hours, 32 mins)

(Runtime: 1 min)

Saturation contours after 50 hours:



Fine-scale model (Runtime: 2 hours, 32 mins)

Two-scale model (Runtime: 1 min)

Saturation contours after 100 hours:



Fine-scale model (Runtime: 2 hours, 32 mins)

Two-scale model (Runtime: 1 min)

Saturation contours after 400 hours:



Fine-scale model (Runtime: 2 hours, 32 mins) Two-scale model (Runtime: 1 min)



Macro mesh: 1116 elements, 608 nodes Micro meshes: 583 elements, 339 nodes

**Total number of unknowns**: 608 + 1116 × 339 = 378,932

Saturation contours after 0 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 1 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 2 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 3 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 4 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 5 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 6 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 7 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 8 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 9 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 10 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 15 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 20 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 25 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 30 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 35 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 40 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 45 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 50 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 60 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 70 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 80 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 90 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 100 hours:



	Number of OpenMP threads					
	1	2	4	8	12	
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43	

Saturation contours after 200 hours:



	Number of OpenMP threads				
	1	2	4	8	12
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43

Saturation contours after 300 hours:



	Number of OpenMP threads				
	1	2	4	8	12
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43

Saturation contours after 400 hours:



	Number of OpenMP threads				
	1	2	4	8	12
Runtime (min:sec) Speedup	40:58 1.00	22:05 1.86	11:55 3.44	07:44 5.30	05:31 7.43

#### Summary

Pros:

- ✓ Ability to capture fine-scale detail in heterogeneous problem
- ✓ Produces good qualitative agreement with fine-scale model
- ✓ Significant reduction in simulation time (compared with fine-scale model)
- ✓ Numerically feasible for problems with very small-scale heterogeneities

Cons:

X Restricted to heterogeneous domains comprised of two sub-domains where one is connected and the other forms disconnected/isolated inclusions

The next stage of this research will investigate two-scale approaches for arbitrary heterogeneous media...

#### Part II: One-dimensional diffusion in a multilayer composite slab

Joint work with Ian Turner (QUT)

#### Fine-scale model

▶ Diffusion in a composite slab consisting of *m* layers:

	Layer 1	Layer 2		Layer $m-1$	Layer m
	$\kappa_1$	$\kappa_2$	$\top$	$\kappa_{m-1}$	$\kappa_m$
$l_0$	) l	1	$l_2$ $l_m$	$l_{m-2}$ $l_m$	$l_{m-1}$ $l_m$

▶ Diffusion equation defined on each layer (i = 1, ..., m):

$$\frac{\partial u_i}{\partial t} = \kappa_i \frac{\partial^2 u_i}{\partial x^2} \qquad l_{i-1} < x < l_i$$

▶ Initial condition  $u_i(x, 0) = f(x)$  and external boundary conditions:

$$a_L u_1(l_0, t) + b_L \frac{\partial u_1}{\partial x}(l_0, t) = c_L \qquad a_R u_m(l_m, t) + b_R \frac{\partial u_m}{\partial x}(l_m, t) = c_R$$

Suitable internal boundary conditions at the interfaces (i = 1, ..., m - 1), e.g.,

$$u_i(l_i, t) = u_{i+1}(l_i, t)$$
  $\kappa_i \frac{\partial u_i}{\partial x}(l_i, t) = \kappa_{i+1} \frac{\partial u_{i+1}}{\partial x}(l_i, t)$ 

▶ Interested in the case when *m* is very large

Example: Composite slab consisting of 100 layers



Macroscopic equation

$$\frac{\partial U}{\partial t} = \frac{\partial F}{\partial x} \qquad l_0 < x < l_m$$

subject to the initial condition U(x, 0) = f(x) and external boundary conditions:

$$a_L U(l_0, t) + b_L \frac{\partial U}{\partial x}(l_0, t) = c_L$$
$$a_R U(l_m, t) + b_R \frac{\partial U}{\partial x}(l_m, t) = c_R$$

is evolved on a coarse grid with unknown macroscopic flux F recovered from solution of the fine-scale model.

Example: Composite slab consisting of 100 layers

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Macroscopic equation

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subject to the initial condition U(x, 0) = f(x) and external boundary conditions:

$$a_L U(l_0, t) + b_L \frac{\partial U}{\partial x}(l_0, t) = c_L$$
$$a_R U(l_m, t) + b_R \frac{\partial U}{\partial x}(l_m, t) = c_R$$

is evolved on a coarse grid with unknown macroscopic flux F recovered from solution of the fine-scale model.

Example: Composite slab consisting of 100 layers



Control volume discretisation in space:

$$\frac{dU_k}{dt} = \frac{F_{k+\frac{1}{2}} - F_{k-\frac{1}{2}}}{x_{k+\frac{1}{2}} - x_{k-\frac{1}{2}}}$$

- Micro-cells are centered around the control volume boundaries
- ► Macroscopic fluxes  $F_{k+\frac{1}{2}}$  and  $F_{k-\frac{1}{2}}$  recovered from the fine-scale solution on the micro-cells (average of fine-scale fluxes)
- Micro-cell boundary conditions depend on the macroscopic field U (what form should these take?)

Example: Composite slab consisting of 100 layers



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$$\frac{dU_k}{dt} = \frac{F_{k+\frac{1}{2}} - F_{k-\frac{1}{2}}}{x_{k+\frac{1}{2}} - x_{k-\frac{1}{2}}}$$

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- Micro-cell boundary conditions depend on the macroscopic field U (what form should these take?)

#### Analytic solution for multilayer diffusion

▶ Exact solution in each layer can be expressed as [Hickson et al. (2009)]:

$$u_i(x,t) = w_i(x) + \sum_{n=0}^{\infty} c_n e^{-t\lambda_n^2} \phi_{i,n}(x)$$

▶ Eigenvalues and eigenfunctions satisfy:

$$\kappa_i \frac{d^2 \phi_{i,n}}{dx^2} + \lambda_n^2 \phi_{i,n} = 0$$

subject to external boundary conditions:

$$a_L\phi_{1,n}(l_0) + b_L \frac{d\phi_{1,n}}{dx}(l_0) = 0, \qquad a_R\phi_{m,n}(l_m) + b_R \frac{d\phi_{m,n}}{dx}(l_m) = 0$$

and internal boundary conditions ( $i = 1, \dots, m - 1$ ):

$$\phi_{i,n}(l_i) = \phi_{i+1,n}(l_i), \qquad \kappa_i \frac{d\phi_{i,n}}{dx}(l_i) = \kappa_{i+1} \frac{d\phi_{i+1,n}}{dx}(l_i)$$

#### Analytic solution for multilayer diffusion

• The eigenfunctions take the form [Ozisik (1968)]:

$$\phi_{i,n}(x) = \alpha_{i,n} \sin\left(\frac{\lambda_n}{\sqrt{\kappa_i}}x\right) + \beta_{i,n} \cos\left(\frac{\lambda_n}{\sqrt{\kappa_i}}x\right)$$

and the eigenvalues  $\lambda_n$  (n = 0, 1, ...) are the positive roots of the transcendental equation:

$$\det(A(\lambda_n)) = 0$$

where A is a  $2m \times 2m$  matrix.

▶ For a large number of layers (large *m*), finding the eigenvalues is infeasible:

*X* computing the determinant is numerically unstable for large matrices*X* run the risk of missing eigenvalues

I couldn't get it working beyond 10 layers

Again, the solution is split into two parts:

$$u_i(x,t) = w_i(x) + v_i(x,t)$$

where  $w_i(x)$  is the steady state solution and  $v_i(x, t)$  satisfies:

$$\frac{\partial v_i}{\partial t} = \kappa_i \frac{\partial^2 v_i}{\partial x^2} \quad l_{i-1} < x < l_i$$

subject to the initial, internal and external boundary conditions:

$$\begin{aligned} v_i(x,0) &= f(x) - w_i(x) \equiv \tilde{f}_i(x), \quad i = 1, \dots, m \\ a_L v_1(l_0, t) + b_L \frac{\partial v_1}{\partial x}(l_0, t) &= 0 \\ a_R v_m(l_m, t) + b_R \frac{\partial v_m}{\partial x}(l_m, t) &= 0 \\ v_i(l_i, t) &= v_{i+1}(l_i, t), \quad i = 1, \dots, m - 1 \\ \kappa_i \frac{\partial v_i}{\partial x}(l_i, t) &= \kappa_{i+1} \frac{\partial v_{i+1}}{\partial x}(l_i, t) \equiv g_i(t), \quad i = 1, \dots, m - 1 \end{aligned}$$

Take Laplace transforms, and assume that the transformed solution can be represented as an orthogonal eigenfunction expansion:

$$\overline{v}_i(x,s) = \sum_{n=0}^{\infty} \langle \overline{v}_i, \phi_{i,n} \rangle \phi_{i,n}(x)$$

where the eigenvalues and eigenfunctions satisfy:

$$\frac{d^2\phi_{i,n}}{dx^2} + \lambda_{i,n}^2\phi_{i,n} = 0$$

subject to boundary conditions local to each layer:

First layer 
$$(i = 1)$$
:  $a_L \phi_{1,n}(l_0) + b_L \frac{d\phi_{1,n}}{dx}(l_0) = 0$  and  $\frac{d\phi_{1,n}}{dx}(l_1) = 0$   
Middle layers  $(i = 2, \dots, m-1)$ :  $\frac{d\phi_{i,n}}{dx}(l_{i-1}) = 0$  and  $\frac{d\phi_{i,n}}{dx}(l_i) = 0$ 

► Last layer 
$$(i = m)$$
:  $\frac{d\phi_{m,n}}{dx}(l_{m-1}) = 0$  and  $a_R\phi_{m,n}(l_m) + b_R\frac{d\phi_{m,n}}{dx}(l_m) = 0$ 

▶ Eigenvalues are roots of simple transcendental equations:

– First layer (
$$i = 1$$
):  $\lambda_{1,n}$  are positive roots of

$$a_L\lambda\sin(\lambda(l_1-l_0)) = -b_L\cos(\lambda(l_1-l_0))$$

– Middle layers (
$$i = 2, ..., m - 1$$
):  $\lambda_{i,n}$  are non-negative roots of

$$\sin(\lambda(l_i - l_{i-1})) = 0$$

- Last layer (
$$i = m$$
):  $\lambda_{m,n}$  are positive roots of

$$a_R\lambda\sin(\lambda(l_m-l_{m-1})) = -b_R\cos(\lambda(l_m-l_{m-1}))$$

▶ Inverting the Laplace transformed solution, the solution within each layer is expressed in terms of inverse Laplace transforms involving the interface functions. For example, in the first layer [Carr and Turner (2015)]:

$$u_1(x,t) = w_1(x) + \sum_{n=0}^{\infty} \left[ c_{1,n} e^{-t\kappa_1 \lambda_{1,n}^2} + \mathcal{L}^{-1} \left\{ \frac{\overline{g}_1(s)}{s + \kappa_1 \lambda_{1,n}^2} \right\} \phi_{1,n}(l_1) \right] \phi_{1,n}(x)$$

▶ Inverse Laplace transforms are computed numerically:

$$\mathcal{L}^{-1}\left\{\frac{\overline{g}_i(s)}{s+\kappa_i\lambda_n^2}\right\} \approx -2\Re\left\{\sum_{k=1}^{N/2} c_{2k-1} \frac{\overline{g}_i(z_{2k-1}/t)}{z_{2k-1}+\kappa_i\lambda_n^2 t}\right\},\,$$

where  $c_{2k-1}$  and  $z_{2k-1}$  are the residues and poles of the best (N - 1, N) rational approximation to  $e^z$  on the negative real line computed using the Carathéodory-Fejér method [Trefethen et al. (2006)].

- Advantages of this approach:
  - ✓ Eigenvalues are roots of simple transcendental equations that are easy to solve numerically
  - ✓ Avoids solving a complicated transcendental equation for the eigenvalues involving the matrix determinant
  - ✓ Scales well to a large number of layers (tested up to 10,000 layers with no problems)

# Application to macroscopic modelling

- ▶ **Fine-scale model**: composite slab consisting of *m* layers
- ▶ **Macroscopic model**: composite slab consisting of *n* layers ( $n \ll m$ ):



$$\frac{\partial U_k}{\partial t} = K_{\text{eff},k} \frac{\partial^2 U_k}{\partial x^2} \qquad L_{k-1} < x < L_k$$

with effective diffusivity (harmonic average) satisfying:

$$\frac{L_k - L_{k-1}}{K_{\text{eff},k}} = \sum_{i \in S_j} \frac{l_i - l_{i-1}}{\kappa_i}$$

where  $S_j$  is the set of micro-layers comprising macro-layer k.

## Application to macroscopic modelling



**Figure:** Micro diffusivities  $\kappa_i = 1.1 + \sin(i)$  (i = 1, ..., 200)

- ▶ Fine-scale model (200 layers): 20 secs runtime
- ▶ Macroscopic model (10 layers): 2 secs runtime

## Application to macroscopic modelling



**Figure:** Micro diffusivities  $\kappa_i = 1.1 + \sin(i)$  (i = 1, ..., 200)

- ▶ Fine-scale model (200 layers): 20 secs runtime
- Macroscopic model (10 layers): 2 secs runtime

#### **Conclusions and Future Outlook**

Two-scale models:

- ▶ are useful for problems involving fine-scale heterogeneities
- can produce excellent agreement with fine-scale solutions with a significant reduction in simulation time

Future work:

- ► Extend the two-scale model for unsaturated water flow in a binary medium to a full two-phase formulation (e.g., air and water or water and oil)
- ► Complete work on two-scale modelling for multilayer diffusion
- Overall goal will be to eventually combine these models to form a generic two-scale model for multiphase transport/flow problems in arbitrary heterogeneous porous media

# Thank you!

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