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Multiscale Modelling of Groundwater Flow

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Joint work with...



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Groundwater Flow



Fine-scale model

► Gradient-driven transport:

$$\frac{\partial \psi}{\partial t} + \nabla \cdot (-K \nabla u) = 0 \quad \text{in } \Omega$$

where ψ and K are functions of $u(\mathbf{x}, t)$.

• Domain Ω comprised of two sub-domains Ω_a (connected) and Ω_b (inclusions):

$$K(u) = \begin{cases} K_a(u) & \text{in } \Omega_a \\ K_b(u) & \text{in } \Omega_b \end{cases}$$
$$\frac{\partial \psi_a}{\partial t} + \nabla \cdot (-K_a \nabla u_a) = 0 \quad \text{in } \Omega_a$$
$$\frac{\partial \psi_b}{\partial t} + \nabla \cdot (-K_b \nabla u_b) = 0 \quad \text{in } \Omega_b$$



Heterogeneous domain $\Omega_a \square \Omega_b \blacksquare$

► Computational cost of direct numerical simulation is prohibitively expensive

Macroscopic averaging



Assumptions:

- 1. At each point $x \in \Omega$, there exists a micro-cell C_x .
- 2. We assume that $C_{x,b}$ is entirely located in the interior of the micro-cell C_x

Macroscopic averaging

Whitaker (1998); Davit et al. (2013)

► Average over the micro-cell:

$$\frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_{x,a}} \frac{\partial \psi_a}{\partial t} \, dV + \frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_{x,a}} \left(\nabla \cdot \boldsymbol{q}_a \right) \, dV = 0$$

▶ Temporal averaging theorem:

$$\frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_{x,a}} \frac{\partial \psi_a}{\partial t} \, dV = \underbrace{\frac{|C_{x,a}|}{|\mathcal{C}_x|}}_{\varepsilon_a} \frac{\partial}{\partial t} \underbrace{\frac{1}{|\mathcal{C}_{x,a}|}}_{\Psi_a} \int_{\mathcal{C}_{x,a}} \psi_a \, dV$$



Spatial averaging theorem:

$$\frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_{x,a}} \left(\nabla \cdot \boldsymbol{q}_a \right) \, dV = \nabla_x \cdot \frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_{x,a}} \boldsymbol{q}_a \, dV - \frac{1}{|\mathcal{C}_x|} \int_{\Gamma_x} \boldsymbol{q}_a \cdot \boldsymbol{n} \, ds$$

Macroscopic (averaged) equations:

$$\varepsilon_a \frac{\partial \Psi_a}{\partial t} + \nabla_x \cdot \boldsymbol{Q}_a = S \qquad \varepsilon_b \frac{\partial \Psi_b}{\partial t} = -S$$

Classical Macroscopic Model

Renard and de Marsily (1997); Szymkiewicz and Lewandowska (2006); Davit et al. (2013)

► Macroscopic Model:

$$\frac{\partial}{\partial t} \left[\varepsilon_a \Psi_a + \varepsilon_b \Psi_b \right] + \nabla_x \cdot \left(-\boldsymbol{K}_{\text{eff}} \nabla_x U \right) = 0$$

where $\Psi_a := \psi_a(U)$ and $\Psi_b := \psi_b(U)$ and U is the macroscopic primary variable.

► Effective conductivity:

$$\left(\boldsymbol{K}_{\text{eff}}\right)_{:,j} = \frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_x} K e_j \, dV + \frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_x} K \nabla_y \chi_j \, dV$$





where χ_j is the solution of the periodic cellproblem on C_x :

$$abla_y \cdot (K \nabla_y (\chi_j + y_j)) = 0, \quad \text{on } \mathcal{C}_x, \quad \text{subject to} \quad \frac{1}{|\mathcal{C}_x|} \int_{\mathcal{C}_x} \chi_j \, dV = 0.$$

Two-scale Model (Model 1)

Showalter (1997); Szymkiewicz and Lewandowska (2008); Carr and Turner (2014)



Macroscopic equation: Microscopic equation:

Microscopic BC:

Source term:

$$\begin{split} \varepsilon_a \frac{\partial \Psi_a}{\partial t} + \nabla_x \cdot (-\mathbf{K}_{\text{eff}} \nabla_x U_a) &= S \,, \quad x \in \Omega \\ \frac{\partial \psi_b}{\partial t} + \nabla \cdot (-K_b \nabla u_b) &= 0 \,, \quad y \in \mathcal{C}_{x,b} \\ u_b &= U_a \,, \quad y \in \Gamma_x \\ S &= -\frac{1}{|\mathcal{C}_x|} \int_{\Gamma_x} \boldsymbol{q}_b \cdot \boldsymbol{n} \, ds \end{split}$$

Two-scale Model (Model 2)



Spatial Discretisation (Model 1)

Carr and Turner (2014); Carr et al. (2016)



Spatial Discretisation (Model 2)



Time discretisation (Model 1 and Model 2)

Carr et al. (2011, 2016); Carr and Turner (2014); Hochbruck et al. (1998)

Spatial discretisation can be expressed in the form:

$$\frac{d\boldsymbol{u}}{dt} = \boldsymbol{g}(\boldsymbol{u}), \quad \boldsymbol{u}(0) = \boldsymbol{u}_0$$

where number of unknowns is very large.

Exponential Euler method:

$$\boldsymbol{u}_{n+1} = \boldsymbol{u}_n + \tau_n \boldsymbol{J}_n^{-1} \big(e^{\tau_n \boldsymbol{J}_n} - \boldsymbol{I} \big) \boldsymbol{g}_n$$

Explicit scheme



Jacobian structure J_n (Zoomed in)

▶ Krylov subspace methods for computing J⁻¹_n(e^{τ_nJ_n − I)g_n converge rapidly without preconditioning, and require only matrix-vector products with J_n:}

$$oldsymbol{J}_n oldsymbol{v} pprox rac{oldsymbol{g}(oldsymbol{u}_n+arepsilonoldsymbol{v})-oldsymbol{g}(oldsymbol{u}_n)}{arepsilon}\,,\quad arepsilonpprox \sqrt{arepsilon_M}\|oldsymbol{u}_n\|_2$$



$$\frac{\partial u_a}{\partial t} + \nabla \cdot (-K_a \nabla u_a) = 0 \quad \text{in } \Omega_a$$
$$\frac{\partial u_b}{\partial t} + \nabla \cdot (-K_b \nabla u_b) = 0 \quad \text{in } \Omega_b$$
$$K_b/K_a = 10^{-p}$$

$$K_b/K_a = 10^{-2}$$



Carr et al. (2016)

 $K_b/K_a = 10^{-4}$



Carr et al. (2016)

 $K_b/K_a = 10^{-4}$





$$\frac{\partial \theta_a}{\partial t} + \nabla \cdot \left[-K_a \left(\nabla h_a + \nabla z \right) \right] = 0 \quad \text{in } \Omega_a$$
$$\frac{\partial \theta_b}{\partial t} + \nabla \cdot \left(-K_b \left(\nabla h_b + \nabla z \right) \right] = 0 \quad \text{in } \Omega_b$$
$$K_b/K_a = 10^{-3}$$









Summary and Conclusions

- Presented a modified two-scale model for gradient-driven transport/flow problems in heterogeneous materials (Model 2)
- ▶ The novel approach avoids the need for an effective parameter in the macroscopic equation by computing the macroscopic flux as the average of the microscopic fluxes over the micro-cell.
- ▶ Numerical experiments demonstrated that both two-scale models (Model 1 and Model 2) produce numerical solutions that are in excellent agreement with the fine-scale model at a reduced computational cost.
- Model 1 requires less computational time
- Model 2 is more accurate and able to capture additional fine-scale features in the solution.

For more details see:

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The extended distributed microstructure model for gradient-driven transport: A two-scale model for bypassing effective parameters



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ABSTRACT

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Keywords:

Two-scale Multiscale Microstructure Dual-scale Heterogeneous Homogenization Numerous problems involving gradient-driven transport processes-e.g., Fourier's and Darcy's law-in heterogeneous materials concern a physical domain that is much larger than the scale at which the coefficients vary spatially. To overcome the prohibitive computational cost associated with such problems, the well-established Distributed Microstructure Model (DMM) provides a two-scale description of the transport process that produces a computationally cheap approximation to the fine-scale solution. This is achieved via the introduction of sparsely distributed micro-cells that together resolve small patches of the fine-scale structure: a macroscopic equation with an effective coefficient describes the global transport and a microscopic equation governs the local transport within each micro-cell. In this paper, we propose a new formulation, the Extended Distributed Microstructure Model (EDMM), where the macroscopic flux is instead defined as the average of the microscopic fluxes within the micro-cells. This avoids the need for any effective parameters and more accurately accounts for a non-equilibrium field in the micro-cells. Another important contribution of the work is the presentation of a new and improved numerical scheme for performing the two-scale computations using control volume. Krylov subspace and parallel computing techniques. Numerical tests are carried out on two challenging test problems; heat conduction in a composite medium and unsaturated water flow in heterogeneous soils. The results indicate that while DMM is more efficient. EDMM is more accurate and is able to capture additional fine-scale features in the solution.

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Thank you!

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